IMPROVING DESIGN EFFICIENCY AND ACCURACY USING 3D MODELING• OTEC 2018





OCTOBER 3, 2018



TO VIEW PRESENTATION ON YOUR MOBILE DEVICE

www.burgessniple.com/ event/2018/otec





IMPROVING DESIGN EFFICIENCY AND ACCURACY USING 3D MODELING

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ODOT District 6



- SR 61, SR 656, Wilson Rd in Delaware
 County
- Posted 55 mph
- Developing area



Image courtesy of Google





32 crashes from 2014 - 2016, including injuries and 1 fatal

- \circ Skew
- o Crest/Sag Combo



Image courtesy of Google



- 5 alternatives studied and presented to public
 - \circ No Build
 - \circ 4-way Stop
 - \circ Signalization
 - \circ Roundabout
 - o SR 61 Profile adjustment

 \circ Roundabout chosen







PROJECT GOALS

Project Goals

- \circ Single-lane roundabout
- Limit R/W at NW and SE quadrants (existing homes)
- Improve vertical geometry approaching intersection

Guidelines

- NCHRP Report 672
- ODOT L&D Volume 1





ROUNDABOUT CONCEPTS

o 3 Roundabout Designs Investigated

 \circ Standard, Oval, Peanut









ROUNDABOUT PERFORMANCE CHECKS - PEANUT SHAPE

- Peanut Roundabout
 chosen
- Improved roundabout geometry
 - o Fastest Path
 - o Phi Angles
 - Angle of visibility
 - Intersection skew





FASTEST PATH

- Encourage slow
 vehicle speeds
- o Turn movements
 - \circ Thru = R1-R2-R3
 - \circ Left = R4
 - \circ Right = R5



Image courtesy of NCHRP 672



PHI ANGLE

• Angle between approach to crossing departure \circ 20° - 30° preferred Short (~3') tangent at approach





SWEPT PATH ANALYSIS (TRUCK TURNS)

- WB-62 design
 vehicle
- Drives truck apron placement/size
- Check for tractor weight shift





OPENROADS

- Roundabout design is iterative
 - Performance checks
 - Swept path (truck turns)
 - Minimize footprint
- OpenRoads = greater
 design efficiency





- Can be used on any type of project
- \circ Best used in iterative design
- Greater efficiency
- Three conceptual roundabout layouts (horizontal, vertical, 3D model) in <u>one</u> <u>week</u>



OPENROADS

OpenRoads and detailed design

- \circ Microstation Add-in
 - o "Smart" linework
 - o 3D emphasis

OpenRoads = Select Series 4





OPENROADS



- Developed using
 OpenRoads
- Can be used for...
 - Conceptual quantities for cost estimate
 - \circ Drive simulation
 - Cross sections and elevations in detailed design





PROFILES

- Graphical profile
 design
- Relate horizontal to vertical
- Linked profiles
- 3D linestring built automatically





PROFILES







STAKEHOLDER ENGAGEMENT

\circ Key Stakeholders

- ODOT District 6
- o DCEO
- Kingston Township
- 3D Model andOpenRoads





BUILDING THE 3D MODEL

Two 3D modeling methods:

- o Corridor Modeling
- \circ Terrain Modeling
- Both methods create
 same output





- Define pavement
 elevations from
 baseline profile
- 3D elements built
 once profile defined
 3D = H+V





BUILDING THE 3D MODEL

- Develop curb,
 grading, etc. from
 templates
- Pavement buildup applied from surface





BUILDING THE 3D MODEL





B&

SOUTHBOUND THROUGH MOVEMENT - 3D MODEL







26 | OTEC 2018

SOUTHBOUND THROUGH MOVEMENT





Ohio Department of **Transportation**

EASTBOUND THROUGH MOVEMENT - 3D MODEL







EASTBOUND THROUGH MOVEMENT







WESTBOUND LEFT TURN MOVEMENT - AUTOTURN







WESTBOUND TO SOUTHBOUND







Cut from 3D model(s)

Viewable during design iterations

\circ Functions as SS2

- o **T-cell**
- \circ Active chain control
- \circ Cross section sheets

Can cut non-perpendicular sections



CROSS SECTIONS







- Developed using
 OpenRoads
- Can be used for...
 - Conceptual quantities for cost estimate
 - \circ Drive simulation
 - Cross sections and elevations in detailed design





OPENROADS FOR QUALITY CONTROL

- 3D model = real
 time design quality
 check
- Linked profiles to ensure vertical tieins match





PROJECT WORKFLOW - GEOPAK SS2





PROJECT WORKFLOW - OPENROADS (SS4)





- OpenRoads improves efficiency in iterative design
- 3D models improve clarity of design and accuracy









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39 | OTEC 2018



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